



SiFive Core IP FPGA Eval Kit User Guide
Version v19.08p0

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SiFive Core IP FPGA Eval Kit User Guide

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Release Information

Version	Date	Changes
v19.08p0	Sept 17, 2019	Updated for 19.08 Core IP Release <ul style="list-style-type: none">• Supports v19.08 Core IP Package• OpenOCD support for the RV32E extension
v2019p05	May 9, 2019	Updated for 19.05 Core IP Release <ul style="list-style-type: none">• Supports v19.05 Core IP Package• Clarified that some GPIOs are not bidirectional when hooked to LEDs/Switches/Buttons• Removed references to Arty 35T (no longer supported)• Added instructions for connecting via cJTAG
v3p0	Feb 28, 2019	Updated for 19.02 Core IP Release <ul style="list-style-type: none">• Supports v19.02 Core IP Package• Added descriptions for Arty-100T• Added Chapters for E2, E3/S5, E7/S7 MCS Images
v2p0	Feb 2, 2018	Updated to match v2p0 of the Evaluation MCS: <ul style="list-style-type: none">• FPGA Eval includes ITIM• DTIM size increased to 64kiB• Number of HWBP increased to 8• Added User Mode Support• Updated various links
v1p0	May 4, 2017	First release

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Chapter 1

Introduction

1.1 About this Document

This document gives necessary information for a user of the SiFive Core IP FPGA Eval Kit. To learn more about the functionality of your specific Core IP please read the appropriate Core IP Manual.

This guide will help you download and flash the Core IP FPGA Eval Kit image to an FPGA development board. It will help you install software tools to allow you to write, upload, and debug code on the Eval Kit. It also contains information about what is contained in the MCS file for the Core IP FPGA Eval Kit.

1.2 About this Release

This Eval Kit allows you to prototype and benchmark your target RISC-V software without modifying, integrating, or synthesizing any Verilog code.

This Core IP FPGA Eval Kit includes .mcs and .bit files to program FPGA flash and RAM respectively with Core IP.

This release is intended for evaluation purposes only.

1.3 Evaluation Version Limitations

Version v19.08 of the Core IP FPGA Eval Kit has the following limitations compared with the fully functional Core IP:

- DTIM is limited in size to 64kB.
- Peripheral Bus, System Bus, and Front Bus are not exported for additional user connections. The evaluation can utilize the peripherals included on the FPGA.
- A fixed number of Local or Global interrupts are exported at the top level.

- Designs without PLIC or CLIC have one added depending on the platform type.
- Designs with APB Debug Interface have JTAG debug interface.
- Refer to your FPGA .dts file for other potential differences.

To target a different FPGA platform or perform synthesis or simulation, you may obtain an Evaluation Version of the Core IP RTL from <https://www.sifive.com>.

Chapter 2

Required Hardware

The Core IP FPGA Eval Kit requires the following hardware:

2.1 Xilinx Arty A7 Artix-7 FPGA Evaluation Kit

The Arty A7 is a Xilinx FPGA development board for makers and hobbyists. The Arty A7 comes in two FPGA variants: The Arty A7-35T features Xilinx XC7A35TICSG324-1L. This board is no longer fully supported. The Arty A7-100T features the larger Xilinx XC7A100TCSG324-1. This is the suggested board for SiFive Core IP evaluation. Both can be purchased from Digilent or Avnet.

<http://www.xilinx.com/products/boards-and-kits/arty.html>

<https://store.digilentinc.com/arty-board-artix-7-fpga-development-board-for-makers-and-hobbyists/>

2.2 USB A to Micro-B Cable

Any standard USB Type A Male to Micro-B Male cable can be used to interface with the Arty. Note that the Arty kit does not include one.

<http://store.digilentinc.com/usb-a-to-micro-b-cable/>

2.3 Olimex ARM-USB-TINY-H Debugger

The Olimex ARM-USB-TINY-H is a hardware JTAG debugger. The Core IP Arty FPGA Dev Kit has a standard JTAG debugging interface, and the tools included with the Core IP FPGA Eval Kit have been tested using the Olimex ARM-USB-TINY-H. It can be purchased from Olimex or Digi-Key.

<https://www.olimex.com/Products/ARM/JTAG/ARM-USB-TINY-H/>

<http://www.digikey.com/product-detail/en/olimex-ltd/ARM-USB-TINY-H/1188-1013-ND/3471388>

2.4 Olimex ARM-JTAG-SWD Adapter

This adapter is only needed if your FPGA uses a cJTAG debug connection rather than JTAG. ARM-JTAG-SWD converts the Olimex probe signals to cJTAG. It is available from Olimex or Digi-Key.

<https://www.olimex.com/Products/ARM/JTAG/ARM-JTAG-SWD/>

<https://www.digikey.com/product-detail/en/olimex-ltd/ARM-JTAG-SWD/1188-1015-ND/3471382>

2.5 USB A to B Cable

Any standard USB Type A Male to B Male cable can be used to interface to the Olimex ARM-USB-TINY-H Debugger. Note that the package does not include one. These are available from a variety of sources, including Digi-Key.

<http://www.digikey.com/product-detail/en/assmann-wsw-components/AK672-2-1/AE1462-ND/930247>

2.6 Male-To-Female Jumper Cables (10)

The connection between the Olimex ARM-USB-TINY-H and Core IP FPGA Eval Kit requires 10 connections. These can be made with Male-to-Female jumper cables. These cables are available from Adafruit in convenient rip-apart ribbon cables:

<https://www.adafruit.com/products/826>

Chapter 3

Board Setup

3.1 Connecting the USB Interface

Connect the USB Type A to Micro-B cable between the USB-JTAG port (J10) of the Arty and the host machine. This provides UART console access to the Core IP FPGA Eval Kit as well as a 5V power source for the board. This is also the interface by which the FPGA fabric will be programmed.

3.2 Connecting the Debugger

The debugger is essential for downloading and debugging code with your SDK. The software will be downloaded to SPI Flash, so it will be retained. Without the debugger you can only flash the FPGA image and run the included demo program, you cannot change the software which executes.

Connect the Olimex ARM-USB-TINY-H with the USB Type A to B cable to the host machine. Then connect the Olimex ARM-USB-TINY-H debugger to PMOD header JD using the 10 jumper cables. The pinout is as shown in Table 1. Note that the Olimex ARM-USB-TINY-H and the PMOD header on the Arty Board have different numbering schemes. Table 2 and Table 3 clarify the different pinouts for the two connectors.

For cJTAG FPGAs, connect the Olimex ARM-USB-TINY-H with the USB Type A to B cable to the host machine. Then plug the Olimex ARM-JTAG-SWD directly into ARM-USB-TINY-H. Then connect the 10 jumper cables as illustrated.

Figure 1 shows what the board looks like with all the debug connections in place.

Note

If using cJTAG please see additional instructions in Freedom-E-SDK Section.

Note

It is important to connect to PMOD header JD (not JA, JB, or JC). JD was selected over the other PMOD headers to avoid damage to the Arty board in the event of mismatched connections.

Signal Name	ARM-USB-TINY-H Pin Number	Suggested Jumper Color	Core IP FPGA Eval Kit JD Pin Number
VREF	1	red	12
VREF	2	brown	6 ("VCC")
nTRST	3	orange	2
TDI	5	yellow	7
TMS/ TMSC	7	green	8
TCK/ TCKC	9	blue	3
TDO	13	purple	1
GND	14	black	5 ("GND")
nRST	15	grey	9
GND	16	white	11

Table 1: Debugging Connections between Olimex ARM-USB-TINY-H and Arty Board's PMOD header JD

	1 : VREF (red)	2 : VREF (brown)
	3 : nTRST (orange)	4
	5 : TDI (yellow)	6
	7 : TMS/TMSC (green)	8
NOTCH	9 : TCK/TCKC (blue)	10
NOTCH	11	12
	13 : TDO (purple)	14 : GND (black)
	15 : nRST (grey)	16 : GND (white)
	17	18
	19	20
	LED	

Table 2: Debug Connections To the Olimex ARM-USB-TINY-H

square pad	1 : TDO (purple)	7 : TDI (yellow)
	2 : nTRST (orange)	8 : TMS/TMSC (green)
	3 : TCK/TCKC (blue)	9 : nRST (grey)
	4	10
"GND"	5 : GND (black)	11 : GND (white)
"VCC"	6 : VREF (brown)	12 : VREF (red)

Table 3: Debug Connections to the Arty Board JD PMOD Header

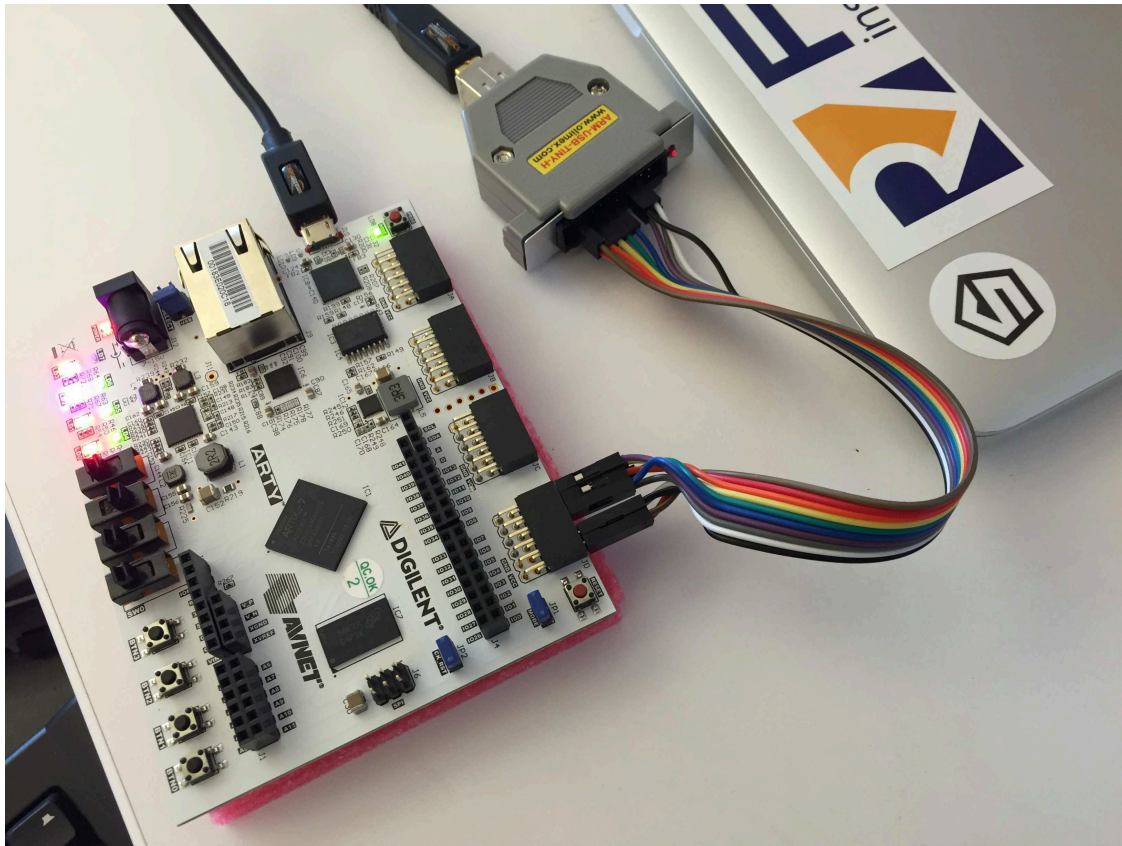


Figure 1: Photo of the Arty Board showing USB and Debug Connections

Chapter 4

FPGA Programming Files

The Xilinx Artix-7 35T or 100T FPGA configures on power-on from an on-board 16MB Quad-SPI Flash.

To program the Arty Board, locate the desired MCS file or BIT file within your Core IP package. The file name is encoded with the coreIP type, Arty type, and version information. For example,

```
sifive_coreip_[XX]_FPGA_Evaluation_Arty_[35|100]T_v[YYY]_rc[ZZ].mcs
```

SiFive Freedom Studio and Xilinx Vivado Design Suite can be used for .mcs flash programming. Only the Xilinx Vivado Design Suite can be used to program a .bit file. A .bit file is raw storage of FPGA information and can be loaded directly onto an FPGA but it does not persist through a power cycle. A .mcs file contains FPGA information, FPGA configuration information, and is stored in non-volatile (flash) memory so it persists through power cycles.

4.1 Using SiFive Freedom Studio

Install the latest Freedom Studio application for your Windows, Mac, or Linux OS from: <https://www.sifive.com/boards>

4.1.1 Windows programming example

Start the .mcs programming tool from Freedom Studio from the main menu bar as shown in Figure 2.

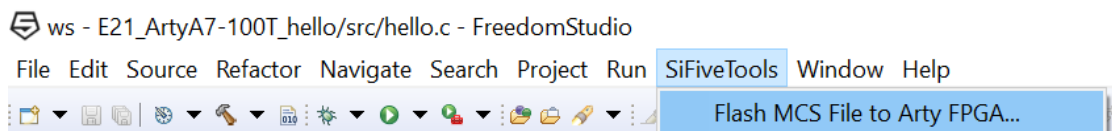


Figure 2: Photo of the Freedom Studio Application showing initiation of .mcs programming

Select the .mcs file and the Arty 35T or 100T as shown in Figure 3.

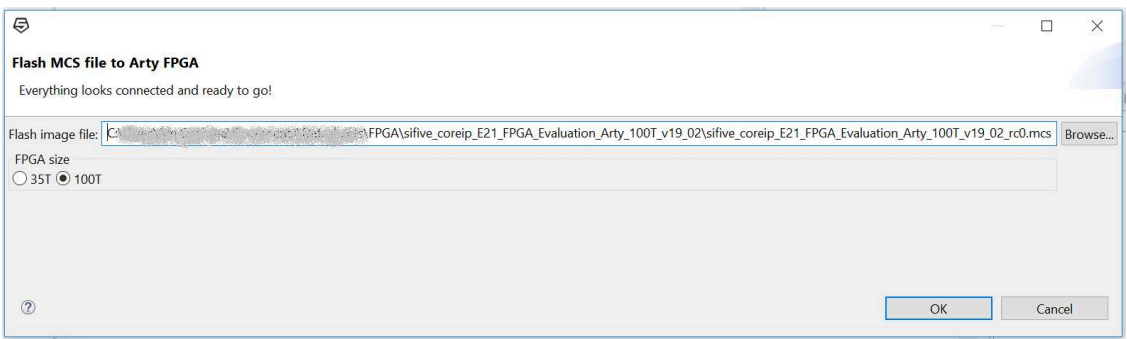


Figure 3: Photo of the Freedom Studio Application showing .mcs and board selection

Freedom Studio may detect that it requires additional drivers and request to install them as shown in Figure 4.

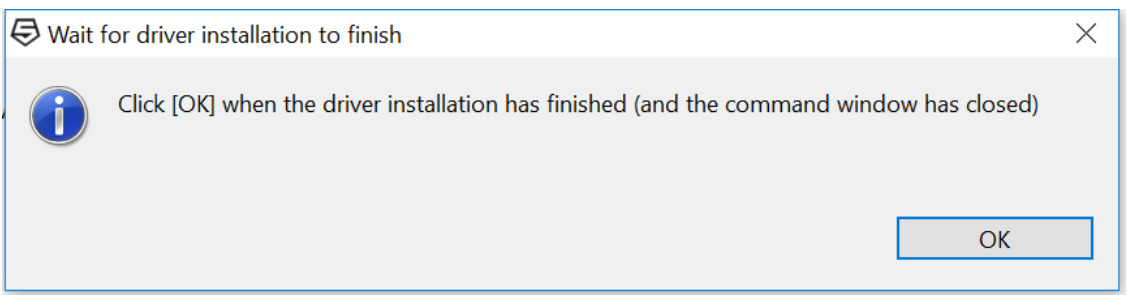


Figure 4: Photo of the Freedom Studio Application showing driver install

Freedom Studio programming the .mcs file on the Arty board as shown in Figure 5.

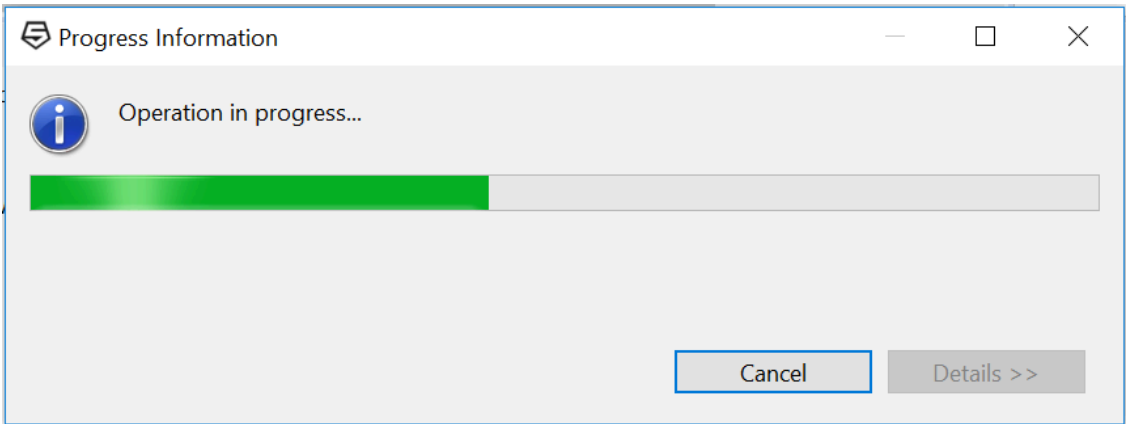


Figure 5: Photo of the Freedom Studio Application showing .mcs flashing operation in progress

Freedom Studio programming .mcs file success as shown in Figure 6.

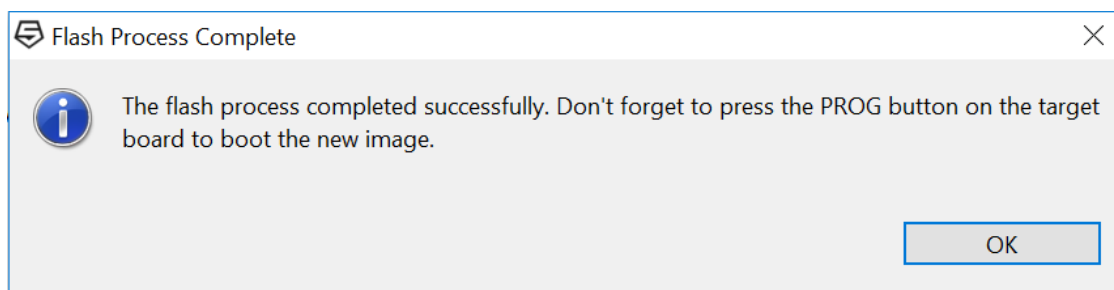


Figure 6: Photo of the Freedom Studio Application showing .mcs flashing operation success

4.2 Using Xilinx Vivado Design Suite

The Xilinx Vivado Design Suite is used for flash programming. Both the Vivado Lab Edition and WebPACK Edition 2018.2 support Artix-7 devices free of charge.

4.2.1 Vivado programming example for an Arty 35T SPI Flash

To program the Arty 35T SPI Flash with Vivado take the following steps:

1. Launch Vivado
2. Open Hardware Manager
3. Open target board
4. Right click on the FPGA device and select “Add Configuration Memory Device”
5. Select the following SPI flash parameters:

Part	m25ql128
Manufacturer	Micron
Alias	n25q128-3.3v-spi-x1_x2_x4
Family	mt25ql
Type	spi
Density	128
Width	x1_x2_x4

6. Click OK to “Do you want to program the configuration memory device now?”
7. Add the MCS file
8. Select OK
9. Once the programming completes in Vivado, press the “PROG” Button on the Arty Board to load the image into the FPGA.

4.2.2 Programming the Arty 100T SPI Flash

To program the Arty 100T SPI Flash with Vivado take the following steps:

1. Launch Vivado
2. Open Hardware Manager
3. Open target board
4. Right click on the FPGA device and select “Add Configuration Memory Device”
5. Select the following SPI flash parameters:

Part	s25fl128sxxxxxx0
Manufacturer	Spansion
Alias	s25fl127s
Family	s25flxxxs
Type	spi
Density	128
Width	x1_x2_x4

6. Click OK to “Do you want to program the configuration memory device now?”
7. Add the MCS file
8. Select OK
9. Once the programming completes in Vivado, press the “PROG” Button on the Arty Board to load the image into the FPGA.

Chapter 5

Boot and Run

5.1 Serial Setup

Using a terminal emulator such as GNU screen on Linux or a terminal on Windows, open a console connection from the host computer to the Core IP FPGA Eval Kit.

Set the following parameters:

Speed	115200
Parity	None
Data bits	8
Stop bits	1
Hardware Flow	None

For example, on Linux using GNU Screen:

```
sudo screen /dev/ttyUSB2 115200
```

You can use `Ctrl-a k` to “kill” (exit) the running screen session.

Depending on your setup, you may need additional drivers or permissions to communicate over the USB port.

If you are running on Ubuntu-style Linux, the below is an example of steps you may need to follow to access your dev kit without sudo permissions:

1. With your board's debug interface connected, make sure your device shows up with the `lsusb` command:

```
> lsusb
...
Bus XXX Device XXX: ID 0403:6011 Future Technology Devices International,
Ltd FT2232C Dual USB-UART/FIFO IC
```

2. Set the udev rules to allow the device to be accessed by the plugdev group:

```
> sudo vi /etc/udev/rules.d/99-openocd.rules
```

Add the following lines and save the file (if they are not already there):

```
# These are for the HiFive1 Board
SUBSYSTEM=="usb", ATTR{idVendor}=="0403",
  ATTR{idProduct}=="6011", MODE="664", GROUP="plugdev"

SUBSYSTEM=="tty", ATTRS{idVendor}=="0403",
  ATTRS{idProduct}=="6010", MODE="664", GROUP="plugdev"

# These are for the Olimex Debugger for use with E310 Arty Dev Kit

SUBSYSTEM=="usb", ATTR{idVendor}=="15ba",
  ATTR{idProduct}=="002a", MODE="664", GROUP="plugdev"

SUBSYSTEM=="tty", ATTRS{idVendor}=="15ba",
  ATTRS{idProduct}=="002a", MODE="664", GROUP="plugdev"
```

3. See if your board shows up as a serial device belonging to the plugdev group:

```
> ls /dev/ttyUSB*
/dev/ttyUSB0 /dev/ttyUSB1 /dev/ttyUSB2 /dev/ttyUSB3
```

(If you have other serial devices or multiple boards attached, you may have more devices listed). For serial communication with the UART, you will always want to select the higher number of the pair, in this example /dev/ttyUSB2.

```
> ls -l /dev/ttyUSB2
crw-rw-r-- 1 root plugdev 188, 1 Nov 28 00:00 /dev/ttyUSB1
```

4. Add yourself to the plugdev group to eliminate the need to sudo for access to the device. You can use the whoami command to determine your user name.

```
> whoami
your_user_name
> sudo usermod -a -G plugdev your_user_name
```

5. Log out and log back in, then check that you're now a member of the plugdev group:

```
> groups
... plugdev ...
```

Now you should be able to access the serial (UART) and debug interface without sudo permissions.

5.1.1 Reset and boot

The FPGA Core IP Eval Kit's boot code contains a jump to the external SPI Flash as described in the DTS file.

For example, an E2/E3 or S5 Core IP FPGA Eval Kit's reset vector is set using Switch 0 on the board. When the switch is "Off" (set towards the edge of the board), the reset vector is set to 0x40400000, which is mapped to the external SPI Flash on the board.

5.1.2 Load a Program

You can change the program which the Eval Kit runs by using the debug/programming interface to flash a new compiled program into the DTIM or SPI Flash.

When Switch 0 is "On" (set away from the edge of the board), the reset vector is set to 0x00000000. This will cause the core to simply wait for the debugger to load a program.

Chapter 6

Software Development Flow

SiFive supports several methods of obtaining the software development toolchain. Freedom Studio is an Eclipse-Based IDE which bundles everything you need into one download. You can also compile the source yourself and run command line tools with the Freedom E SDK.

These different development versions will all install the same set of tools, but the versions, install paths and associated software libraries and examples are different for each.

6.1 Supported Platforms

Freedom Studio is supported on Linux, macOS, and Windows.

6.2 Software Development Using Freedom Studio IDE

SiFive recommends software development for the Core IP FPGA Eval Kit with the Eclipse-based Freedom Studio IDE. Freedom Studio is supported for Windows, macOS, and Linux. When using this method, the precompiled tools and drivers are automatically installed, you do not need to download or install it separately to get tools and example code.

You can obtain Freedom Studio from the SiFive website:

<https://www.sifive.com/boards>

More information on how to use it can be found in the Freedom Studio Manual:

<https://www.sifive.com/documentation/tools/freedom-studio-manual>

6.3 Software Development Using Freedom E SDK Command Line Tools

Freedom-E-SDK is a public github repository, maintained by SiFive Inc, that makes it easy to get started developing software for SiFive's Freedom and RISC-V Core IP Platforms. The SDK supports a wide array of SiFive Core IPs, SoCs and Emulation environments.

<https://github.com/sifive/freedom-e-sdk>

This section describes how to set up the toolchain and configure the SDK. The section also walks through building an example program and executing it in the RTL testbench included in a SiFive Core IP deliverable.

Note

SiFive Core IP deliverables downloaded from the SiFive site already include a ready-to-use version of Freedom E SDK. Installation from github is not required.

In addition, the section will walk through how to import custom BSPs and build a program using the custom BSP target.

6.3.1 Setting Up Freedom-E-SDK

Prerequisites

To use this SDK, you will need the following software available on your machine:

- GNU Make
- Git

Toolchain Prerequisites

To build examples and programs, you will need the following software installed on your machine:

- RISC-V GNU Toolchain
- RISC-V OpenOCD (for use with development board and FPGA targets)

Pre-built versions of these softwares can be found on the SiFive Website.

<https://www.sifive.com/boards>

The pre-built tools have been carefully packaged to support both RISC-V 32bit & 64bit ISAs and work on Linux, macOS, and Windows hosts.

Download the toolchain your platform, and unpack it to your desired location. Then, use the RISC_V_PATH and RISC_V_OPENOCD_PATH variables when using the tools.

For example,

```
> cp openocd-<date>-<platform>.tar.gz /my/desired/location/
> cp riscv64-unknown-elf-gcc-<date>-<platform>.tar.gz /my/desired/location
> cd /my/desired/location
> tar -xvf openocd-<date>-<platform>.tar.gz
> tar -xvf riscv64-unknown-elf-gcc-<date>-<platform>.tar.gz
> export RISC_V_OPENOCD_PATH=/my/desired/location/openocd
> export RISC_V_PATH=/my/desired/location/riscv64-unknown-elf-gcc-<date>-<version>
```

If you are configuring a toolchain included with a SiFive Core IP deliverables package, set the following environment variables:

```
> export RISC_V_OPENOCD_PATH=/my/desired/location/openocd
> export RISC_V_PATH=/my/desired/location/riscv64-unknown-elf-gcc-<date>-<version>
```

6.3.2 Cloning the Repository

The Freedom-E-SDK repository can be cloned by running the following commands:

```
> git clone --recursive https://github.com/sifive/freedom-e-sdk.git
> cd freedom-e-sdk
```

The recursive option is required to clone the git submodules included in the repository. If at first you omit the recursive option, you can achieve the same effect by updating submodules using the command:

```
> git submodule update --init --recursive
```

6.4 Freedom E SDK Arty BSP

The Freedom Metal Compatibility Library layer uses the board support package files to provide the hardware abstraction layer. These BSP files can be found under the bsp folder in Freedom-E-SDK and are encapsulated entirely within each target directory. The supported targets are:

- SiFive Freedom E310 Arty
- freedom-e310-arty

SiFive CoreIP Arty FPGA Evaluation targets

- coreip-eXX-arty
- coreip-sXX-arty

Note

The SiFive Core IP deliverables package includes a single FPGA Evaluation target, `design-arty`. If you are using this package, you must set your selected build to `TARGET=design-arty`.

For example, the board support files may consist of the following:

*****design.dts*****

The DeviceTree description of the target. This file is used to parameterize the Freedom Metal library to the target device. It is included as reference so that users of Freedom Metal are aware of what features and peripherals are available on the target.

*****metal.h*****

The Freedom Metal machine header which is used internally to Freedom Metal to instantiate structures to support the target device.

*****metal.lds*****

The linker script for the target device.

`openocd.cfg` (for development board and FPGA targets)

Used to configure OpenOCD for flashing and debugging the target device.

If not using Freedom Studio and using the cJTAG debug interface do the following. In the generated `openocd.cfg` file add the following lines after "interface ftdi":

```
interface ftdi

ftdi_oscan1_mode on
ftdi_layout_signal TCK -data 0x0001
ftdi_layout_signal TDI -data 0x0002
ftdi_layout_signal TDO -input 0x0004
ftdi_layout_signal TMS -data 0x0008
ftdi_layout_signal JTAG_SEL -data 0x0100 -oe 0x0100
```

This is necessary for the Olimex to convert to cJTAG. Freedom Studio has this included by default.

*****settings.mk*****

Used to set march and mabi arguments to the RISC-V GNU Toolchain.

6.5 Example Programs

Some example programs can be found under `software`:

*****hello*****

Prints "Hello, World!" to stdout, if a serial device is present on the target.

*****return-pass*****

Returns status code 0 indicating program success.

*****return-fail*****

Returns status code 1 indicating program failure.

*****example-itim*****

Demonstrates how to statically link application code into the Instruction Tightly Integrated Memory (ITIM) if an ITIM is present on the target.

*****software-interrupt*****

Demonstrates how to register a handler for and trigger a software interrupt

*****timer-interrupt*****

Demonstrates how to register a handler for and trigger a timer interrupt

*****local-interrupt*****

Demonstrates how to register a handler for and trigger a local interrupt

*****example-pmp*****

Demonstrates how to configure a Physical Memory Protection (PMP) region

6.6 Using the Freedom E SDK

6.6.1 Building an Example

To compile a bare-metal RISC-V program:

```
make PROGRAM=timer-interrupt TARGET=coreip-s51-arty software
```

The square brackets in the above command indicate optional parameters for the Make invocation.

To compile a bare-metal RISC-V program for a target included with your tarball:

```
make PROGRAM=timer-interrupt TARGET=design-arty software
```


6.6.2 Uploading to the Target Board

```
make [PROGRAM=hello] [TARGET=coreip-s51-arty] upload
```

6.6.3 Debugging a Target Program

```
make [PROGRAM=hello] [TARGET=coreip-s51-arty] debug
```

6.6.4 Cleaning a Target Program Build Directory

```
make [PROGRAM=hello] [TARGET=coreip-s51-arty] clean
```

6.6.5 Create a Standalone Project

You can export a program to a standalone project directory using the standalone target. The resulting project will be locked to a specific TARGET.

STANDALONE_DEST is a required argument to provide the desired project location.

```
make standalone [PROGRAM=hello] [TARGET=coreip-s51-arty]  
  STANDALONE_DEST=/path/to/desired/location
```

Once the standalone project is created, it can be compiled simply by typing make.

```
cd /path/to/desired/location standalone  
make
```

Run make help for more commands.

Chapter 7

E2/S2 Core IP FPGA Eval Kit MCS Image Contents

Figure 7 shows a block diagram of the E2 Core IP FPGA Eval Kit. The same diagram applies for S2 FPGA images.

The evaluation kit includes an evaluation Core IP along with additional peripherals and I/Os to allow software prototyping.

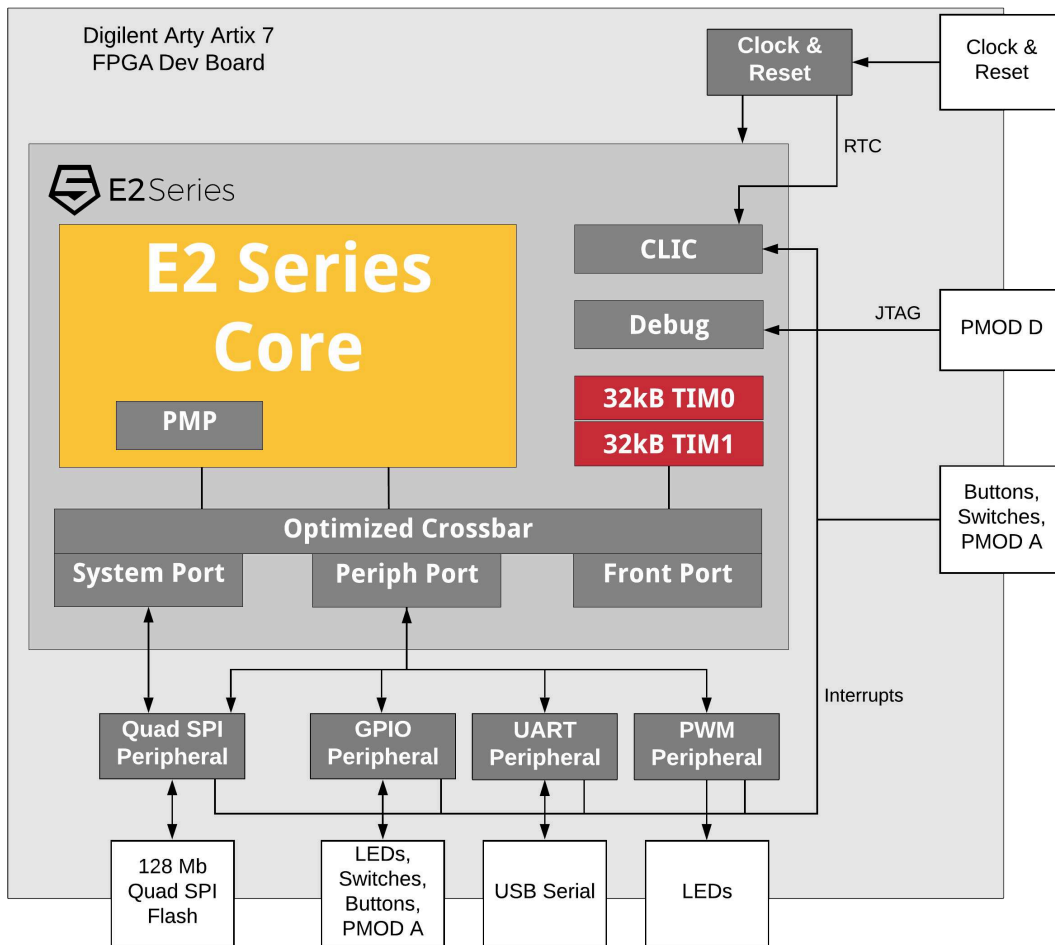


Figure 7: E2/S2 Core IP FPGA Eval Kit Block Diagram

7.1 Core IP FPGA Eval Kit Memory Map

The FPGA design on the Core IP FPGA Eval Kit has an evaluation version of the SiFive E2/S2 Core IP, as well as peripheral devices which are not included with the Core IP deliverable. These devices allow you to perform basic I/O to prototype and benchmark some basic applications.

Please refer to the Device Tree file, (.dts) for details of the Memory Map and interrupt mapping.

7.2 Core IP FPGA Eval Kit Clock and Reset

The Core IP FPGA Eval Kit has a 100MHz input to the FPGA. This is used to derive the Core IP's `io_coreClock` at 32.5 MHz, and the `clock` (peripheral clock) at 32.5 MHz. The `io_rtcToggle` is driven at approximately 32 kHz.

The system reset driven by the Reset Button on the evaluation board is combined with the external debugger's SRST_n pin as a full system reset for the Core IP FPGA Eval Kit. This is combined with the io_ndreset to drive the reset input to the Core IP.

The reset vector is set with Switch 0. Leave the switch in the “Off” position to execute from SPI Flash.

7.3 Core IP FPGA Eval Kit Pinout

The peripherals perform I/O functionalities and are also used to demonstrate the use of Global Interrupts. The peripheral devices are connected to hardware on the Arty development board as described in Table 4. Some inputs are wired directly as Global Interrupts, while others go through the GPIO peripheral.

In addition, some board I/Os are configured as Local Interrupt sources. The mapping between hardware on the Core IP FPGA Eval Kit and Local Interrupt sources are provided in Table 5

Peripheral	Peripheral Offset	Connections
UART	UART TX/RX	To USB Serial
	SWITCH 0	Direct Global Interrupts
	SWITCH 1	
	SWITCH 2	
	SWITCH 3	
Quad SPI	all QSPI	To Quad SPI Flash
GPIO	GPIO[0] (Output Only)	LED 0 RED
	GPIO[1] (Output Only)	LED 0 GREEN
	GPIO[2] (Output Only)	LED 0 BLUE
	GPIO[3] (Input Only)	SWITCH 3
	GPIO[4] (Input Only)	BUTTON 0
	GPIO[5] (Input Only)	BUTTON 1
	GPIO[6] (Input Only)	BUTTON 2
	GPIO[7] (Input Only)	BUTTON 3
	GPIO[8]	PMOD B[0]
	GPIO[9]	PMOD B[1]
	GPIO[10]	PMOD B[2]
	GPIO[11]	PMOD B[3]
	GPIO[12]	PMOD B[4]
	GPIO[13]	PMOD B[5]
	GPIO[14]	PMOD B[6]
	GPIO[15]	PMOD B[7]
PWM/Counter	PWM CMP[0]	
	PWM CMP[1]	LED 1 RED
	PWM CMP[2]	LED 1 GREEN
	PWM CMP[3]	LED 1 BLUE
Non Core IP System Indicators	System Reset	LED[4]
	Debugger SRST_n	LED[5]
	dmactive	LED[6]

Table 4: Core IP FPGA Eval Kit GPIO Offset to Board Pin Number

Hardware Input	Local Interrupt Number (Index in mip, mie, registers)
UART	16
SPI	17
GPIO 0-15	18-33
PWM CMP 0-3	34-37
Global Ext Int 0: SW 0	38
Global Ext Int 1: SW 1	39
Global Ext Int 2: SW 2	40
Global Ext Int 3: SW 3	41
Global Ext Int 4-7 (NC)	42-45
Local Ext Int 0: Switch 0	46
Local Ext Int 1: Switch 1	47
Local Ext Int 2: Switch 2	48
Local Ext Int 3: Switch 3	49
Local Ext Int 4: Button 0	50
Local Ext Int 5: Button 1	51
Local Ext Int 6: Button 2	52
Local Ext Int 7: Button 3	53

Table 5: Core IP FPGA Eval Kit Local External Interrupts Mapping

Chapter 8

E3 / S5 Core IP FPGA Eval Kit MCS Image Contents

Figure 8 shows a block diagram of the E3 / S5 Core IP FPGA Eval Kit.

The evaluation kit includes an evaluation Core IP along with additional peripherals and I/Os to allow software prototyping.

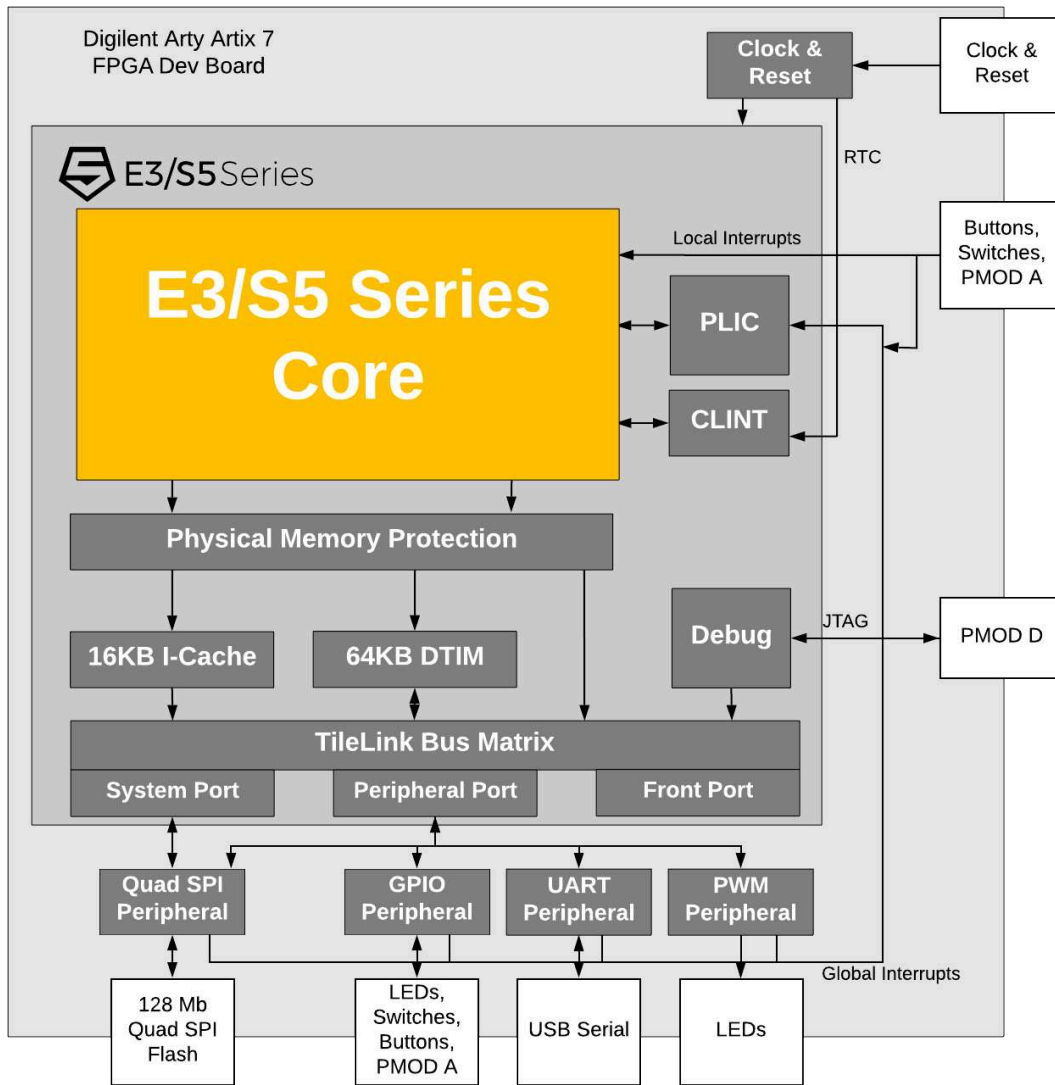


Figure 8: E3 / S5 Core IP FPGA Eval KitBlock Diagram

8.1 Core IP FPGA Eval Kit Memory Map

The FPGA design on the Core IP FPGA Eval Kit has an evaluation version of the SiFive E3 / S5 Core IP, as well as peripheral devices which are not included with the Core IP deliverable. These devices allow you to perform basic I/O to prototype and benchmark some basic applications.

Please refer to the Device Tree file, (.dts) for details of the Memory Map and interrupts.

8.2 Core IP FPGA Eval Kit Clock and Reset

The Core IP FPGA Eval Kit has a 100MHz input to the FPGA. This is used to derive the Core IP's `io_coreClock` at 32.5 MHz, and the `clock` (peripheral clock) at 32.5 MHz. The `io_rtcToggle` is driven at approximately 32 kHz.

The system reset driven by the Reset Button on the evaluation board is combined with the external debugger's `SRST_n` pin as a full system reset for the Core IP FPGA Eval Kit. This is combined with the `io_ndreset` to drive the reset input to the Core IP.

The reset vector is set with Switch 0. Leave the switch in the "Off" position to execute from SPI Flash.

8.3 Core IP FPGA Eval Kit Pinout

The peripherals perform I/O functionalities and are also used to demonstrate the use of Global Interrupts. The peripheral devices are connected to hardware on the Arty development board as described in Table 6. Some inputs are wired directly as Global Interrupts, while others go through the GPIO peripheral.

In addition, some board I/Os are configured as Local Interrupt sources. The mapping between hardware on the Core IP FPGA Eval Kit and Local Interrupt sources are provided in Table 7

Peripheral	Peripheral Offset	Connections	Global Interrupt Number
UART	UART TX/RX	To USB Serial	1
	SWITCH 0	Direct Global Interrupts	23
	SWITCH 1		24
	SWITCH 2		25
	SWITCH 3		26
Quad SPI	all QSPI	To Quad SPI Flash	2
GPIO	GPIO[0] (Output Only)	LED 0 RED	3
	GPIO[1] (Output Only)	LED 0 GREEN	4
	GPIO[2] (Output Only)	LED 0 BLUE	5
	GPIO[3]	SWITCH 3	6
	GPIO[4]	BUTTON 0	7
	GPIO[5]	BUTTON 1	8
	GPIO[6]	BUTTON 2	9
	GPIO[7]	BUTTON 3	10
	GPIO[8]	PMOD B[0]	11
	GPIO[9]	PMOD B[1]	12
	GPIO[10]	PMOD B[2]	13
	GPIO[11]	PMOD B[3]	14
	GPIO[12]	PMOD B[4]	15
	GPIO[13]	PMOD B[5]	16
	GPIO[14]	PMOD B[6]	17
	GPIO[15]	PMOD B[7]	18
PWM/Counter	PWM CMP[0]		19
	PWM CMP[1]	LED 1 RED	20
	PWM CMP[2]	LED 1 GREEN	21
	PWM CMP[3]	LED 1 BLUE	22
Non Core IP System Indicators	System Reset	LED[4]	
	dmactive	LED[6]	
	internal Reset	LED[7]	

Table 6: Core IP FPGA Eval Kit GPIO Offset to Board Pin Number

Hardware Input	Local Interrupt Number (Index in mip, mie, registers)
Button 0	16
Button 1	17
Button 2	18
Button 3	19
Switch 0	20
Switch 1	21
Switch 2	22
Switch 3	23

Table 7: Core IP FPGA Eval Kit Local Interrupts Mapping

Chapter 9

E7 / S7 Core IP FPGA Eval Kit MCS Image Contents

Figure 9 shows a block diagram of the E7 / S7 Core IP FPGA Eval Kit.

The evaluation kit includes an evaluation Core IP along with additional peripherals and I/Os to allow software prototyping.

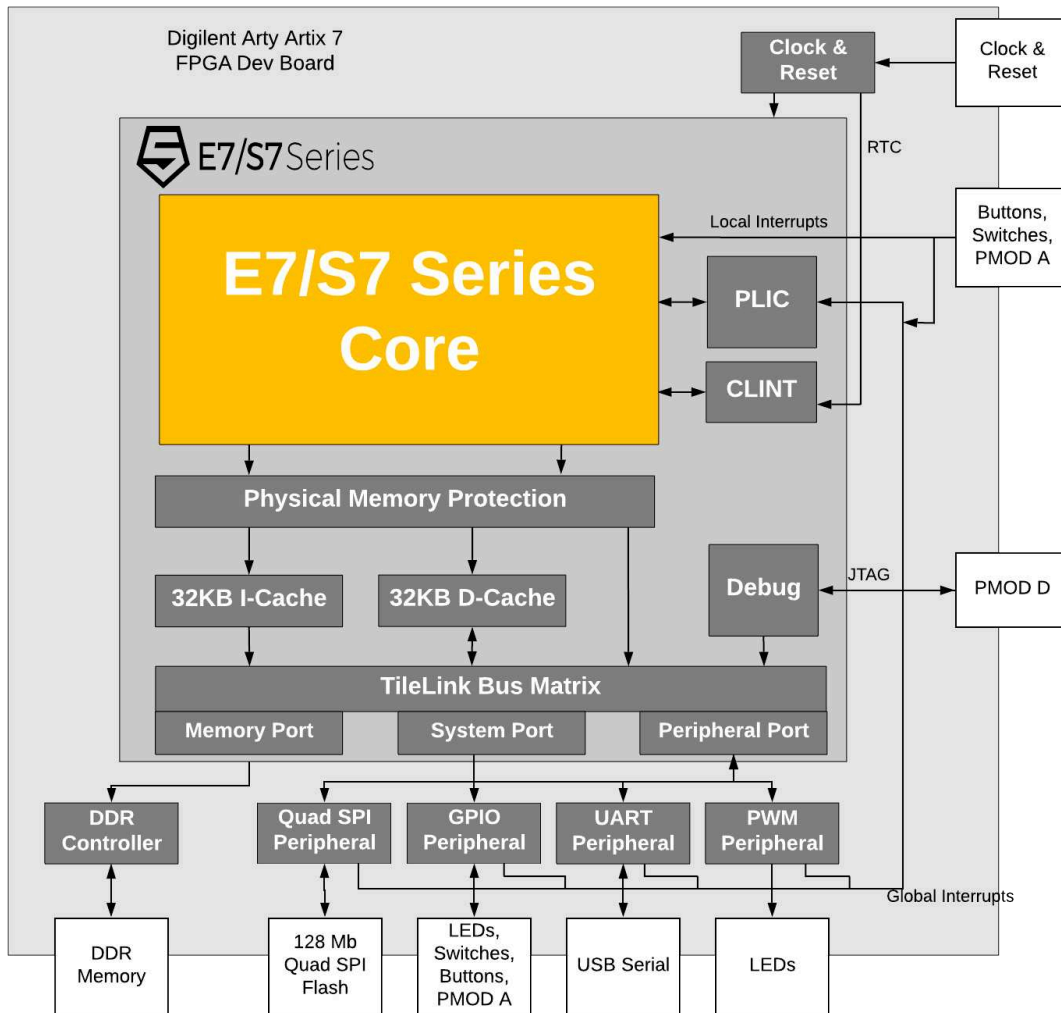


Figure 9: E7 / S7 Core IP FPGA Eval Kit Block Diagram

9.1 Core IP FPGA Eval Kit Memory Map

The FPGA design on the Core IP FPGA Eval Kit has an evaluation version of the SiFive E7 / S7 Core IP, as well as peripheral devices which are not included with the Core IP deliverable. These devices allow you to perform basic I/O to prototype and benchmark some basic applications.

Please refer to the Device Tree file, (.dts) for details of the Memory Map and interrupts.

9.2 Core IP FPGA Eval Kit Clock and Reset

The Core IP FPGA Eval Kit has a 100MHz input to the FPGA. This is used to derive the Core IP's `io_coreClock` at 32.5 MHz, and the `clock` (peripheral clock) at 32.5 MHz. The `io_rtcToggle` is driven at approximately 32 kHz.

The system reset driven by the Reset Button on the evaluation board is combined with the external debugger's `SRST_n` pin as a full system reset for the Core IP FPGA Eval Kit. This is combined with the `io_ndreset` to drive the reset input to the Core IP.

9.3 Core IP FPGA Eval Kit Pinout

The peripherals perform I/O functionalities and are also used to demonstrate the use of Global Interrupts. The peripheral devices are connected to hardware on the Arty development board as described in Table 8. Some inputs are wired directly as Global Interrupts, while others go through the GPIO peripheral.

Peripheral	Peripheral Offset	Connections	Global Interrupt Number
UART	UART TX/RX	To USB Serial	1
	SWITCH 0	Direct Global Interrupt	23
	SWITCH 1		24
	SWITCH 2		25
	SWITCH 3		26
Quad SPI	all QSPI	To Quad SPI Flash	2
GPIO	GPIO[0] (Output Only)	LED 0 RED	3
	GPIO[1] (Output Only)	LED 0 GREEN	4
	GPIO[2] (Output Only)	LED 0 BLUE	5
	GPIO[3] (Input Only)	SWITCH 3	6
	GPIO[4] (Input Only)	BUTTON 0	7
	GPIO[5] (Input Only)	BUTTON 1	8
	GPIO[6] (Input Only)	BUTTON 2	9
	GPIO[7] (Input Only)	BUTTON 3	10
	GPIO[8]	PMOD B[0]	11
	GPIO[9]	PMOD B[1]	12
	GPIO[10]	PMOD B[2]	13
	GPIO[11]	PMOD B[3]	14
	GPIO[12]	PMOD B[4]	15
	GPIO[13]	PMOD B[5]	16
	GPIO[14]	PMOD B[6]	17
	GPIO[15]	PMOD B[7]	18
PWM/Counter	PWM CMP[0]		19
	PWM CMP[1]	LED 1 RED	20
	PWM CMP[2]	LED 2 GREEN	21
	PWM CMP[3]	LED 3 BLUE	22
Non Core IP System Indicators	System Reset	LED[4]	
	dmactive	LED[6]	
	Internal Reset	LED[7]	

Table 8: Core IP FPGA Eval Kit GPIO Offset to Board Pin Number

Chapter 10

For More Information

Additional information, the latest version of this guide, and supporting files can be found at <https://www.sifive.com>.

More information about RISC-V in general is available at

<http://riscv.org>

SiFive thoughts, ideas, and news at

<https://www.sifive.com/blog/>

Webinars at

<https://info.sifive.com/risc-v-webinar>